## Y800 ${ }^{\text {Plus }}$

## Custom ASCII Protocol Serial Communications

## INSTRUCTION MANUAL



## Now with Ethernet

Yokoyawa Corporation of America

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## 2. INTRODUCTION, CUSTOM ASCII SERIAL PROTOCOL

The Custom ASCII Protocol is a simple serial communications protocol which is optimized for use with our programmable digital panel meters, counters, timers and transmitters.

Digital panel meters, counters and timers accept an optional serial communications plug-in board, which can be any of the following:

- RS232 board
- RS485 board with dual RJ11 jacks.
- RS485 board with dual RJ45 jacks
- USB board
- USB-to-RS485 converter board
- Ethernet board
- Ethernet-to-RS485 converter board

Our two RS485 meter boards use the same circuitry and support the same serial protocols. The boards with dual RJ11 jacks can be daisy-chained using readily available, straight-through 6-wire data cables (not 4-wire telephone cables or crossover cables). Dual RJ45 jacks are available for use with Modbus, as recommended in the Modbus Specification. With either board, the two jacks are wired in parallel to allow daisy chaining of meters with no need for a hub. External repeaters can be used to increase the number of addressable meters.

Our USB-to-RS485 and Ethernet-to-RS485 converter boards allow the host meter to function as a normal meter, be connected to a host computer or Ethernet local area network (LAN), and also act as the device server for an RS485 network of up to 31 meters. These should be equipped with RS485 board with RJ11 connectors for daisy chaining with 6 -wire data cables.

Our DIN-rail transmitters come with either an Ethernet or RS232/RS485 I/O port as ordered. This is in addition to a scalable 4-20 mA output and dual relays, which are standard.

Our DIN-rail Ethernet-to-RS485 device server provides an RJ45 jack for connection to the Ethernet, an RJ11 jack to support an RS485 network of meters, plus screw terminals to support an RS485 network of DIN-rail transmitters via a set of 3 or 5 parallel wires (half- or full-duplex).

The Modbus Protocol, described in a different manual, is a software-selectable alternative to the Custom ASCII Protocol. It is fully compliant with Modbus over Serial Line Specification V1.0 (2002). It is an industry standard which allows devices by different manufacturers to be digitally addressed on the same network. However, it is more complex than the Custom ASCII Protocol and is only recommended when Modbus compatibility is required. In Ethernet networks, the Modbus TCP protocol is seamlessly converted to Modbus RTU or Modbus ASCII by our Ethernet software. Note: Modbus is not supported by our weight meter.

USB connection of multiple meters to a PC can be via a USB hub or up to 5 hubs in series. Each USB connection is then automatically assigned a virtual com port number, which can be addressed via software. The USB standard specifies the maximum length of a USB cable as 5 meters ( 16 ft ).

A better way to connect multiple meters to a PC USB port is to install an isolating USB-to-RS485 converter board in the first meter and to daisy chain multiple meters each with an RS485 board. Use a standard USB cable, Male Type A to Male Type B, to connect the PC to the server
 meter. The RJ11 output of each RS485 meter can then be connected to the next meter via a 6conductor straight-through data cable. Up to 30 additional meters may be daisy chained and be addressed using the Custom ASCII Protocol.

To connect a meter with a USB board to a Windows PC, use a USB cable with Type A and Type B connectors. Upon first connection, your computer may display "Found new Hardware" and automatically download and install the required USB driver from the Internet. If installation is not automatic, download the driver file (with a name like CDM v2.10.00 WHQL Certified.zip) from
 http://www.ftdichip.com/Drivers/VCP.htm. Unzip it into its own directory, and point to that directory as the location of the driver. You will need to use Device Manager (accessible from Control Panel) to determine the com port. Go down the device list and click on Ports (COM \& LPT) and USB serial port (com \#). Note the com port \# for use with communications to your meter, then exit Control Panel. If you later need to change the Com port, right-click on USB serial port (com \#), then on Properties, Port settings, and Advanced. Change port to the desired number, click OK, then exit Control Panel.

Ethernet connection of meters and transmitters requires device configuration via our Node Manager Software, a Windows-based application that runs on a host computer. Node Manager automatically discovers all Nodes on a LAN or WAN, plus any devices connected to each Server Node via an RS485 bus. It is used to configure each Node, such as setting communication parameters, naming the Node and associated devices, entering email addresses for alarm notification and data requests, selecting the Node's time zone for time-stamping of emails and streaming data, and upgrading firmware. Once configuration data has been stored in flash memory of all Nodes, Node Manager Software can be closed. Please see our separate Ethernet Manual.

## 3. SERIAL CONNECTION EXAMPLES




## 4. JUMPER SETTINGS \& FIELD WIRING

## 1. SAFETY WARNINGS <br> 

Digital panel meters, counters, timers and transmitters may be powered with AC (mains) from 85-264 Vac or $95-300 \mathrm{Vdc}$ with standard high voltage power, or $12-34 \mathrm{~V}$ ac or $10-48 \mathrm{Vdc}$ with the low voltage power supply option. To avoid the possibility of electrical shock or damaging short circuits, always unplug the device before opening the case. Please refer to the respective device manuals for full safety information and instruction on how to open the case. Signal wiring changes external to the case can be made safely while the units are under power.

## 2. JUMPERS ON SERIAL METER BOARDS

## USB Board \& Basic Ethernet Board <br> No jumpers needed.



RS232 Board
e-Normal operation.
f - Slave display to RS232 from another meter.
g-Pull-up resistor on RTS line.
Note: Board is shipped with jumpers $\mathbf{e}$ and $\mathbf{g}$ installed
RS485-Modbus Board, Full Duplex Operation
b \& e - Bias jumpers should be installed on 1 board.
a \& d - Installed on last meter in long cable run.
RS485-Modbus Board, Half Duplex Operation
b \& e - bias jumpers installed on 1 board.
$\mathbf{c} \& \mathbf{f}$ - installed for half duplex operation.
a - installed on last meter in line with long cable runs.


Note: Board is shipped with no jumpers installed.

## RS485 Board, Full Duplex Operation

b \& d - Installed on last meter in long cable run.
RS485 Board, Half Duplex Operation
a \& c - Installed for half duplex operation.
d - Installed on last meter in line with long cable runs.
Note: Board is shipped with no jumpers installed.


Ethernet-to-RS485 Device Converter Board \& USB-to-RS485 Device Converter Board Full Duplex Operation

No jumpers for short cable runs.


Add $\mathbf{b}$ \& d for long cable runs.

## Half Duplex Operation

a \& c - Installed for half duplex operation.
d - Installed on last meter in line with long cable runs.


## 3. CONNECTOR WIRING, SERIAL BOARD TO COMPUTER

RS232 INTERFACE Computer


RS485 INTERFACE - FULL DUPLEX


RS485-MODBUS - FULL DUPLEX



RJ11-to-DB9 RS232 cable with rear view of DB9 connector to PC

RS485 INTERFACE - HALF DUPLEX


RS485-MODBUS - HALF DUPLEX


## 4. TRANSMITTER CONNECTOR WIRING



RS485 RS232
6 N/C
5 ARX
4 ATX
3 GND
$2 B R X$


1 BTX
N/C
3 Power GND
2 AC neutral or -DC
RS232 cable with rear view of DB9 connector to PC 1 AC high or +DC


* The termination resistor jumper settings should only be selected if the transmitter is the last device on an RS485 line Ionger than 200 feet ( 60 m ).
** Or jumper external BTX to BRX and ATX to ARX (same effect as internal jumpers).

| Serial Signal | Duplex | Jumpers | Termination Resistor* |
| :---: | :---: | :---: | :---: |
| RS485 | Full | None | E6 $a=$ Transmit <br> E6 $\mathrm{c}=$ Receive |
|  | Half | $\mathrm{E} 6 \mathrm{~b}+\mathrm{d}^{* *}$ | E6 c |
| RS232 | Full | None | None |


| Serial Signal | Duplex | Jumpers | Termination Resistor* |
| :---: | :---: | :---: | :---: |
| RS485 | Full | None | E6 $a=$ Transmit <br> E6 $\mathrm{c}=$ Receive |
|  | Half | E6 $\mathrm{b}+\mathrm{d}^{* *}$ | E6 c |
| RS232 | Full | None | None |

* The termination resistor jumper settings should only be selected if the transmitter is the last device on an RS485 line longer than 200 feet ( 60 m ).
** Or jumper external BTX to BRX and ATX to ARX (same effect as internal jumpers).
To reset communications to 9600 baud, command mode, Custom ASCII protocol, and Address 1, place a jumper at E1 and power up the transmitter.

| Analog Output | Jumpers |
| :---: | :---: |
| Current | E2 $a+d$ |
| Voltage | E2 $b+c$ |


| Excitation Output $^{*}$ | Jumpers |
| :---: | :---: |
| $5 \mathrm{~V}, 100 \mathrm{~mA}$ | $\mathrm{E} 3 \mathrm{a}+\mathrm{c} ; \mathrm{E} 4 \mathrm{a}$ |
| $10 \mathrm{~V}, 120 \mathrm{~mA}$ | $\mathrm{E} 3 \mathrm{a}+\mathrm{c} ; \mathrm{E} 4 \mathrm{~b}$ |
| $24 \mathrm{~V}, 50 \mathrm{~mA}$ | $\mathrm{E} 3 \mathrm{~b}, \mathrm{E} 4$ none |

* Attempting to draw more than the rated current will shut down the output.


## 5. PROGRAMMING YOUR SERIAL DEVICE

## OVERVIEW

Digital panel meters, counters, timers and transmitters are easily programmed via their serial port using Windows-based Instrument Setup (IS) software, which provides a graphical user interface and is available at no charge. This software allows uploading, editing, downloading and saving of setup data, execution of commands under computer control, listing, plotting and graphing of data, and computer prompted calibration. Digital panel meters, counters and timers can also be programmed via their 4-key front panel as explained in their respective manuals. For Ethernet, please see our separate Ethernet Manual.

## GETTING STARTED WITH INSTRUMENT SETUP SOFTWARE

To install IS software, download the file instrument.exe from our website, double-click on the file name to extract three files, double-click on setup.exe, and follow the prompts. To launch IS software, press Start => Programs => IS2 => IS2. Establish communications by selecting matching settings between the instrument and PC, and click on Establish. Once communications have been established, click on Main Menu.

The best way to learn IS software is to experiment with it. From the Main Menu, click on Get Setup to retrieve (or get) the existing setup data from your device. Click on View $=>$ Setup to bring up screens which allow you to edit the setup file using pull-down menus and other selection tools. You can save your file to disk by clicking on File = > Save Setup. You can download (or put) your edited file into the device by clicking on Put Setup. Programmable items will only be displayed if the appropriate hardware has been detected, such as the dual relay option for meters. Pressing the F1 key at any time will bring up detailed help information.

An analog output is defined in two steps. The input to the device is first scaled to a digital reading in engineering units, and this reading is then scaled to the analog output. The digital reading is also used for setpoint control and can be transmitted as serial data.

## ADDITIONAL FEATURES

- The Commands pull-down menu allows you to execute certain functions by using your computer mouse. The Commands pull-down menu will be grayed out unless a Get Setup has been executed.
- The Readings pull-down menu provides three formats to display input data on your PC monitor. In all formats, use the Pause and Continue buttons to control the timing of data collection, then press Print for a hardcopy on your PC printer. List presents the latest digital readings in a 20 -row by 10 -column table. Plot generates a plot of digital readings vs. time in seconds, like an oscilloscope. Graph generates a histogram, where the horizontal axis is the reading and the vertical axis is the number of readings.


## 6. FRONT PANEL SETUP, SERIAL COMMUNICATIONS

### 6.1 FRONT PANEL SETUP, DIGITAL PANEL METERS \& SCALE METER ONLY

| $\xrightarrow{\text { MENU }} \xrightarrow{\text { Press Menu }}$ Select Key | PEAK Press Digit Select Key | Reset Press Value Select Key |
| :---: | :---: | :---: |
| SEr 1 <br> Press $\boldsymbol{\longrightarrow}$ until <br> Ser 1 is displayed. <br> Fixed Parameters: <br> - No parity <br> - 8 data bits <br> - 1 stop bit |  | 0 Send unfiltered signal <br> 1 Send filtered signal |
|  |  | $\mathbf{0}$ 300 baud <br> $\mathbf{1}$ 600 baud <br> $\mathbf{2}$ 1200 baud <br> $\mathbf{3}$ 2400 baud <br> $\mathbf{4}$ 4800 baud <br> $\mathbf{5}$ 9600 baud <br> $\mathbf{6}$ 19200 baud |
|  | 000 <br> Output update rate, Continuous Data Output Mode. |  $\frac{60 \mathrm{~Hz}}{}$ $\underline{50 \mathrm{~Hz}}$ <br> $\mathbf{0}$ 0.017 sec 0.020 sec <br> $\mathbf{1}$ 0.28 sec 0.34 sec <br> $\mathbf{2}$ 0.57 sec 0.68 sec <br> $\mathbf{3}$ 1.1 sec 1.4 sec <br> $\mathbf{4}$ 2.3 sec 2.7 sec <br> $\mathbf{5}$ 4.5 sec 5.4 sec <br> $\mathbf{6}$ 9.1 sec 10.9 sec <br> $\mathbf{7}$ 18.1 sec 21.8 sec <br> $\mathbf{8}$ 36.6 sec 43.5 sec <br> $\mathbf{9}$ 72.5 sec 86.7 sec |
| SEr 2 <br> Serial Setup 2 | $\begin{aligned} & \mathbf{0 0 0 0} \\ & \hline \text { Line feed } \end{aligned}$ | 0 No <LF> following <CR> 1 <LF> following <CR> |
|  | 0000 <br> Alarm data with readings | 0 No alarm data with reading 1 Alarm data with reading |
|  | 0000 <br> Control of data output | 0 Continuous data output <br> 1 Data output on ASCII command only |
|  | 0000 <br> Meter address | Select 1 thru F for addresses 1 thru 15. Select 0. thru F. (with decimal point) for addresses 16 thru 31. |


| $\xrightarrow{M E N U}$ Press Menu | PEAK Press Digit Select Key | reset Press Value Select $\square$ Key |
| :---: | :---: | :---: |
| SEr 3 <br> Serial Setup 3 | RS485 half or full duplex | 0 Full duplex 1 Half duplex |
|  | 00000 <br> Special start \& stop char. (entered using Instrument Setup Software) | 0 * Start, <CR> Stop characters Special Start \& Stop characters |
|  | 00000 <br> RTS mode (for RS232) | 0 Normal non-latching RTS <br> 1 Single transmission, latching RTS |
|  | 00000 <br> Termination characters | 0 Only at end of all items 1 At end of each item |
|  | 00000 <br> Data sent, digital panel meter only | 0 Reading <br> 1 Peak <br> 2 Valley <br> 3 Reading + Peak <br> 4 Reading + Valley <br> 5 Reading + Peak + Valley |
|  | 00000 <br> Data sent, scale meter only | 0 Net + Gross <br> Net only <br> Gross only <br> Peak only (Net or Gross) <br> Net + Gross + Peak <br> Valley only |
| SEr 4 <br> Serial Setup 4 | 000 <br> Modbus ASCII gap timeout* | $\mathbf{0}$ 1 sec $\mathbf{2}$ 5 sec <br> $\mathbf{1}$ 3 sec $\mathbf{3}$ 10 sec |
|  | 000 <br> Serial protocol | $\begin{array}{\|ll} \hline \mathbf{0} & \text { Custom ASCII } \\ \mathbf{1} & \text { Modbus RTU* } \\ 2 & \text { Modbus ASCII* } \end{array}$ |
|  | $\begin{gathered} 000 \\ \hline \text { Parity } \end{gathered}$ | $\mathbf{0}$ None <br> $\mathbf{1}$ Odd (Modbus only) <br> 2 Even (Modbus only) |
| Addr <br> Modbus Address* | $0000=000=000$ | 158 <br> Select 0 through 9 for flashing digit. Address range is 1 to 247 . |

* Modbus is not applicable to our weight meter.


### 6.2 FRONT PANEL SETUP, COUNTERS \& TIMERS ONLY

| $\xrightarrow{M E N U}$Press Menu <br> $\square$ | Press Digit Select Key | reset Press Value Select Key |
| :---: | :---: | :---: |
| Ser 1 <br> Serial Setup 1. <br> Press $\longrightarrow$ until <br> Ser 1 is displayed. <br> Fixed Parameters <br> - No parity <br> - 8 data bits <br> - 1 stop bit | $000$ | 0 Send unfiltered signal 1 Send filtered signal |
|  | $\begin{gathered} 000 \\ \overline{\text { Baud rate }} \end{gathered}$ | $\mathbf{0}$ 300 baud  $\mathbf{4}$ <br> $\mathbf{1}$ 4800 baud   <br> $\mathbf{1}$ 600 baud 5 9600 baud <br> $\mathbf{2}$ 1200 baud 备 19200 baud <br> $\mathbf{3}$ 2400 baud   |
|  | 000 <br> Output update rate, Continuous Data Output Mode. |  $\frac{60 \mathrm{~Hz}}{0.017 \mathrm{sec}}$ $\underline{50 \mathrm{~Hz}}$ <br> $\mathbf{0} 0.020 \mathrm{sec}$   <br> $\mathbf{0}$ 0.28 sec 0.34 sec <br> $\mathbf{2}$ 0.57 sec 0.68 sec <br> $\mathbf{3} 1.1 \mathrm{sec}$ 1.4 sec  <br> $\mathbf{4} 2.3 \mathrm{sec}$ 2.7 sec  <br> $\mathbf{5}$ 4.5 sec 5.4 sec <br> $\mathbf{6}$ 9.1 sec 10.9 sec <br> $\mathbf{7}$ 18.1 sec 21.8 sec <br> $\mathbf{8}$ 36.6 sec 43.5 sec <br> $\mathbf{9}$ 72.5 sec 97 sec |
| Ser 2 <br> Serial Setup 2 | $\begin{gathered} 0000 \\ \hline \text { Line feed } \end{gathered}$ | 0 No <LF> after <CR> 1 <LF> after <CR> |
|  | $0000$ <br> Alarm data with readings | 0 No alarm data <br> 1 Alarm data with reading |
|  | 0000 <br> Control of data output | 0 Continuous data output <br> 1 Data output on ASCII command only |
|  | $0000$ <br> Meter address with Custom ASCII protocol | Select 1 thru F for addresses 1 thru 15. Select 0. thru (with decimal point) for addresses 16 thru 31. |
| Ser 3 <br> Serial Setup 3 | 00000 RS485 half or full duplex | $\begin{array}{ll}0 & \text { Full duplex } \\ 1 & \text { Half duplex }\end{array}$ |
|  | $00000$ <br> Special start \& stop char. (entered using Instrument Setup Software) | 0 Standard continuous mode <br> 1 Special start \& stop characters |


| $\xrightarrow{M E N U}$ Press Menu | Peak $\begin{aligned} & \text { Press Digit Select } \\ & \text { Key }\end{aligned}$ | ${ }_{\text {RESET }}$ Press Value Select Key |
| :---: | :---: | :---: |
| Ser 3 | 00000 <br> RTS mode for RS232 | 0 Normal non-latching RTS <br> 1 Single transmission, latching RTS |
|  | $\begin{aligned} & 00000 \\ & \text { Termination characters } \end{aligned}$ | 0 Only at end of all items 1 At end of each item |
|  | 00000 <br> Data sent in continuous mode | 0 All active items 1 Item \#1 only 2 Item \#2 only (if active) 3 Item \#3 only (if active) 4 Peak only 5 Displayed item 6 Valley only $\underline{7}$ All active items + Peak |
| Ser 4Serial Setup 4 | 000 <br> Modbus ASCII gap timeout | $\mathbf{0}$ 1 sec <br> $\mathbf{1}$ 3 sec <br> $\mathbf{2}$ 5 sec <br> $\mathbf{3}$ 10 sec |
|  | $000$ | $\begin{array}{\|ll} \hline \mathbf{0} & \text { Custom ASCII } \\ \mathbf{1} & \text { Modbus RTU } \\ \boldsymbol{2} & \text { Modbus ASCII } \end{array}$ |
|  | $\frac{000}{\text { Parity }}$ | $\begin{array}{\|ll} \hline \mathbf{0} & \text { None } \\ \mathbf{1} & \text { Odd (Modbus only) } \\ \mathbf{2} & \text { Even (Modbus only) } \end{array}$ |
| Addr <br> Modbus Address | $000 \quad 000 \quad 000$ | 158 <br> Select 0 thru $\mathbf{9}$ for flashing digit. Address range is 1 to 247 . |

## 7. CUSTOM ASCII COMMUNICATION PROTOCOL

### 7.1 SERIAL COMMUNICATION FORMAT

The Custom ASCII serial communication format for RS232, RS485 and USB is the following:
Duplex $\qquad$ Full duplex for RS232 \& RS485. Half duplex selectable for RS485.
Baud Rate $\qquad$ 300, 600, 1200, 2400, 4800, 9600, 19200 selectable by front panel Menu item "Ser 1", Sub-menu item "Digit 4" for DPM, "Digit 5" for counter.
Parity None
Word length 8 data bits
Stop bit $\qquad$ 1

### 7.2 MEASUREMENT DATA FORMAT

The basic measurement data format consists of 8 ASCII characters for the DPM, such as <SP>999.99 <CR> and 9 characters for the counter, such as <SP> 9999.99<CR>, where <SP> is the space character and <CR> is the carriage return character. The first character is always a space character or minus sign. A decimal point is always furnished, even when it follows the last digit.

## Adding a Line Feed Character to the Basic Format

Printers and other devices that receive the measurement data may require a line feed character <LF> following the <CR>. The line feed character may be selected in "Ser 2".

## Adding a Coded Data Character to the Basic Format

It is possible to add a coded character from A to $h$ to the data string according to the table to the right to indicate the alarm and overload status of the device. If used, this character precedes the <CR>, so it is the last printable character in the string. With the optional <LF> and coded character selected, the data string will consist of 10 characters for the DPM: <SP>999.99A<CR><LF> and 11 characters for the counter: <SP>9999.99A<CR><LF>.

For example, a coded character " $G$ " indicates that Alarm 2 only is set and that the DPM is in overload condition. This information is useful when data is

| Alarm \# |  |  |  | Alarm with No Overload | Alarm with Overload |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 00 | 0 | A | E |
| 0 | 0 | 0 | 1 | B | F |
| 0 | 0 | 01 | 10 | C | G |
| 0 | 0 | 01 | 11 | D | H |
| 0 | 0 | 10 | 0 | I | M |
| 0 | 01 | 10 | 1 | J | N |
| 0 | 0 | 11 | 10 | K | 0 |
| 0 | 0 | 11 | 11 | L | P |
| 1 | 1 | 00 | 0 | Q | U |
| 1 | 10 | 00 | 1 | R | V |
| 1 | 1 | 01 | 10 | S | W |
| 1 | 1 | 01 | 11 | T | X |
| 1 | 1 | 10 | 0 | a | e |
| 1 |  | 10 | 1 | b | f |
| 1 | 1 | 11 | 10 | c | g |
| 1 | 1 | 11 | 11 | d | h | supplied to a computer for listing and analysis, or when data is supplied to a Remote Display in a Master-Slave configuration.

The Counter and Scale Meter are capable of supplying more than 1 measurement value (or "Item") with each reading, as selected in "Ser 3". In the counter, there can be up to 3 Items plus Peak and Valley values, depending on the selected Function. The scale meter can transmit Net, Gross and Peak weight.
Values are transmitted in a continuous string with no space between them. If the $5^{\text {th }}$ digit in "Ser 3 " is set to 1 , the termination characters of $<C R>$ and optional <LF> appear after each value. If the $5^{\text {th }}$ digit is et to 0 , the termination characters appear only once at the end of the string. In either case, if included, the coded character appears at the end of the last value only.

### 7.3 NETWORK CONFIGURATIONS

The meters and transmitters can operate in a point-to-point mode using RS-232 or RS-485, or in a multi-point mode using RS-485.

The point-to-point mode is a direct connection between a computer (or other digital device) and the meter or transmitter.

The multi-point mode is a connection from a host computer to a multiplicity of meters or transmitters bused together with their inputs and outputs connected in parallel. For long cable runs, the first and last devices should have a termination resistor installed. It is necessary to set up each device on the bus with a different address from 1 to 31 . To command a particular device, its address is used in conjunction with the command, and only that device responds. The outputs of all of the devices on the bus are set to a high impedance state, except the device being addressed. The device addresses range from 1 to 31 . A special address to which all meters respond is 0 and should not be used in the multi-point mode. Addressing of meters can be set in "Ser 2".

A device operating in a point-to-point mode must also be addressed. Although any address will suffice, it is suggested address $=1$ be selected as a standard for the point-to-point mode.

### 7.4 OPERATING MODES

The meters and transmitters can operate in a Continuous Mode or a Command Mode.
In the Continuous Mode, measurements are continuously transmitted by the meter in a standard data format. Please see the next manual section.

In the Command Mode, the meter does not send any data automatically, but responds to commands received from a host computer. Please see the manual section following the Continuous Mode.

## 8. CONTINUOUS MODE

### 8.1 OVERVIEW

In the Continuous Operating Mode, measurements are continuously transmitted by the meter or transmitter in a standard data format using printable ASCII characters at a user-selectable rate ranging from 50 or 60 Hz line frequency down to one measurement every 72 seconds. This data may be received by a remote display at a distant location, by a printer for data logging purposes, or by a host computer for data analysis or system control.

Both hardware (RTS) and software (XON/XOFF) handshaking are available for RS232, but neither is available for RS485.

### 8.1 METERS OR TRANSMITTERS WITH DPM OR SCALE METER MAIN BOARD

The transmission rate of the measurement data can be selected in "Ser 1". The meter conversion rate equals the AC power frequency ( 50 or 60 Hz ). Any baud rate may be used, but if less than the minimum baud rate in the table, the transmission rate will decrease accordingly.

| Output Rate | Data Output Rate | Minimum Baud Rate |  |  |
| :---: | :---: | :---: | :---: | :---: |
| "Ser 1" Setting | $\mathbf{5 0 ~ H z} / \mathbf{6 0 ~ H z}$ | 1 Item Sent | 2 Items Sent | 3 Items Sent |
| 0 | $0.021 \mathrm{~s} / .018 \mathrm{~s}$ | 9600 | 9600 | 19200 |
| 1 | $0.34 \mathrm{~s} / 0.28 \mathrm{~s}$ | 600 | $600 / 1200$ | 1200 |
| 2 | $0.68 \mathrm{~s} / 0.57 \mathrm{~s}$ | 300 | $300 / 600$ | 600 |
| 3 | $1.4 \mathrm{~s} / 1.1 \mathrm{~s}$ | 300 | 300 | 300 |
| 4 | $2.7 \mathrm{~s} / 2.3 \mathrm{~s}$ | 300 | 300 | 300 |
| 5 | $5.4 \mathrm{~s} / 4.5 \mathrm{~s}$ | 300 | 300 | 300 |
| 6 | $10.9 \mathrm{~s} / 9.1 \mathrm{~s}$ | 300 | 300 | 300 |
| 7 | $21.8 \mathrm{~s} / 18.1 \mathrm{~s}$ | 300 | 300 | 300 |
| 8 | $43.5 \mathrm{~s} / 36.3 \mathrm{~s}$ | 300 | 300 | 300 |
| 9 | $86.7 \mathrm{~s} / 72.3 \mathrm{~s}$ | 300 | 300 | 300 |

### 8.2 METERS OR TRANSMITTERS WITH COUNTER / TIMER MAIN BOARD

The transmission rate of the measurement data can be selected in "Ser 1". Data transmission is initiated at the end of the calculation time following the gate time. Data is completely transmitted for one measurement before the calculation of the next measurement is started. Therefore, the reading rate is influenced by the baud rate, the number of items transmitted, and gate time. If the selected gate time is less than that shown in the table below, it is not the determining factor of the reading rate. If it is greater, then it is the determining factor. Time intervals (reciprocal of rate) between transmissions at the reading rate are:

| Baud <br> Rate | Time <br> 1 Item | Min <br> Gate | Time <br> 2 Items | Min <br> Gate | Time <br> 3 Items | Min <br> Gate | Time <br> 4 Items | Min <br> Gate |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 300 | 0.37 s | 0.34 s | 0.70 s | 0.67 s | 10.03 s | 1.00 s | 1.37 s | 1.34 s |
| 600 | 0.18 s | 0.15 s | 0.35 s | 0.32 s | 0.52 s | 0.49 s | 0.68 s | 0.65 s |
| 1200 | 0.09 s | 0.06 s | 0.18 s | 0.15 s | 0.26 s | 0.23 s | 0.34 s | 0.31 s |
| 2400 | 0.05 s | 0.02 s | 0.09 s | 0.06 s | 0.13 s | 0.10 s | 0.17 s | 0.14 s |
| 4800 | 0.02 s | 0.01 s | 0.04 s | 0.01 s | 0.07 s | 0.04 s | 0.09 s | 0.06 s |
| 9600 | 0.01 s | 0.01 s | 0.02 s | 0.01 s | 0.03 s | 0.01 s | 0.04 s | 0.01 s |
| 19200 | 0.01 s | 0.01 s | 0.01 s | 0.01 s | 0.02 s | 0.01 s | 0.01 s | 0.01 s |

The data transmission rate may be reduced by sending data every other reading, every fourth reading, or less. This selection is made in "Ser 1". A computer, if busy with other tasks, may be unable to keep up with the faster data rates of the meter, so a handshake function is available that provides the computer with control over the meters' data transmissions.

### 8.3 RTS CONTROL

RTS control does not apply to transmitter, where the RTS line is always held high, nor to RS485. DPMs and counter / timers have two RS232 RTS modes: unlatched and latched. These modes are selected in "Ser3".

In the unlatched mode, the measurement transmission is enabled by a high RTS level and is disabled by a low RTS level. When disabled, any character being sent is completed. When enabled, any characters remaining in the data format are transmitted before the next measurement transmission. The computer, when its receive buffer is nearly full, takes the RTS line low to halt data transmission. When its receive buffer has emptied, it takes the RTS line high to enable more data transmissions. Some measurements could be missed in the process. In the latched mode, the RTS input is polled every 3.3 ms . When a high level is detected, RTS is latched true, even though the RTS line goes low immediately. At the end of each calculation, the latched RTS value is checked. If it is true, a complete measurement transmission (from 1 to 4 values) is made without interruption, regardless of the state of the RTS line during that time. At the end of the complete transmission, the latched RTS value is reset false, even though the RTS line may be high at that instant. The RTS latch does not go true again until the RTS line is first returned to a low level after the completion of the transmission and then is taken high again. Latched control provides "print command" operation by sending a transmission for each RTS pulse. If a second pulse occurs during the transmission, it is not recognized.

### 8.3 XON / XOFF CONTROL

Applicable to RS232, not RS485. A measurement transmission is enabled by the receipt of an ASCII XON character. It is disabled by the receipt of an ASCII XOFF character.

## 9. COMMAND MODE

### 9.1 OVERVIEW

In the Command Mode, the device does not send any data automatically, but responds to commands received from a host computer. These commands can be:

- To transmit the latest, peak, or valley measurement.
- To reset the meter completely or just the peak and valley values and latched alarms.
- To display a value sent from the computer.
- To transmit present setup parameters.
- To receive new setup parameters.
- To monitor or alter data in selected memory locations of the meter.

The selection of either the Continuous mode or the Command Mode can be made from the front panel Menu selection "Ser 2". The meter will not respond to a command in the Continuous Mode, except the command "A1", which puts the meter into the Command Mode.

### 9.2 COMMAND MODE FORMAT

The minimum format is 4 characters. Example: *5A1
After any command that causes a Meter Reset, such as CO, F, W, X, the Counter sends an "R" character after the Reset is complete and the Counter is ready to accept a new command.

## CHAR 1 - COMMAND IDENTIFIER

All commands begin with "*" followed by the meter address, then a command letter followed by a sub-command number or letter. Additional characters may be appended. All commands terminate with <CR> (<LF> ignored). The counter may be assigned a different recognition character via the RS232 / 485 serial port, but will still recognize the "*".

| Char \# | Character | Description |
| :---: | :---: | :--- |
| 1 | $*$ | Command Identifier (Recognition Character) |
| 2 | $0-V$ | Device Address (0 addresses all devices, 1-V specific) |
| 3 | A-Z | Command Function |
| 4 | $0-U$ | Sub-command (or \# Bytes or Words of data being transferred) |

## CHAR 2 - ADDRESS CODES

The next table is the Serial Communication Address Codes following the "*" for each meter address number. Also shown is the corresponding character that is set in menu item "SER 2".

| Meter \# | Meter SER 2 <br> Digit 5(6) | Serial Comm <br> Address Code |
| :---: | :---: | :---: |
| 1 | 1 | 1 |
| 2 | 2 | 2 |
| 3 | 3 | 3 |
| 4 | 4 | 4 |
| 5 | 5 | 5 |
| 6 | 6 | 6 |
| 7 | 7 | 7 |
| 8 | 8 | 8 |
| 9 | 9 | 9 |
| 10 | A | A |
| 11 | B | B |
| 12 | C | C |
| 13 | D | D |
| 14 | E | E |
| 15 | F | F |
|  |  |  |


| Meter \# | Meter SER 2 <br> Digit 5(6) | Serial Comm <br> Address Code |
| :---: | :---: | :---: |
| 16 | 0. | G |
| 17 | 1. | H |
| 18 | 2. | I |
| 19 | 3. | J |
| 20 | 4. | K |
| 21 | 5. | L |
| 22 | 6. | M |
| 23 | 7. | N |
| 24 | 8. | 0 |
| 25 | 9. | P |
| 26 | A. | Q |
| 27 | B. | R |
| 28 | C. | S |
| 29 | D. | T |
| 30 | E. | U |
| 31 | F. | V |

## CHARS 3 \& 4-COMMANDS AND SUBCOMMANDS

The examples below use a default address of 1 following the "*". Substitute the desired address from the above table of Serial Comm Address Codes. All command sequences shown must terminate with <CR>, followed by an optional <LF>.

## COMMUNICATIONS MODE

| Continuous mode | ${ }^{* 1} 1$ A0 |
| :--- | :--- |
| Command mode | ${ }^{* 1} 11$ |

## REQUEST DPM VALUES

Get reading**
*1B1
Peak reading *1B2
Valley reading
*1B3
** The meter transmits the value or values selected in Ser 3.

## REQUEST SCALE METER VALUES

| Get reading** | ${ }^{*} 1 \mathrm{~B} 1$ |
| :--- | :--- |
| Net only | ${ }^{* 1} 1 \mathrm{~B} 2$ |
| Gross only | ${ }^{* 1} 1 \mathrm{~B} 3$ |
| Peak only | ${ }^{* 1} 1 \mathrm{~B} 4$ |

** The meter transmits the value or values selected in Ser 3.

## REQUEST COUNTER VALUES

| All active items 1, 2 or 3 | *1B0 |
| :---: | :---: |
| Item 1 | *1B1 |
| Item 2 | *1B2 |
| Item 3 | *1B3 |
| Peak | *1B4 |
| Displayed item | *1B5 |
| Valley | *186 |
| All active items + Peak + Valley | *1B7 |

## RESET FUNCTIONS, DPM \& SCALE METER

| Cold reset | *1C0 | Reads NVMEM into RAM locations after RAM is zeroed. |
| :---: | :---: | :---: |
| Latched alarms reset | *1C2 |  |
| Peak value reset | *1C3 |  |
| Remote display reset | *1C4 |  |
| External Input B true | *1C5 |  |
| External Input B false | *1C6 |  |
| External Input A true | *1C7 |  |
| External Input A false | *108 |  |
| Valley reset | *1C9 |  |
| Tare function | *1CA |  |
| Tare reset | *1CB |  |
| RESET FUNCTIONS, COUNTER / TIMER |  |  |
| Cold reset | *100 | Reads NVMEM into RAM locations after RAM zeroed. |
| Function reset | *1C1 | Resets all total values and/or peak value. |
| Latched alarms reset | *1C2 |  |
| Peak value reset | *1C3 |  |
| Remote display reset | *1C4 | Resets Item 3 to zero if not Arith or Batch. Removes Alarm View or Peak View if on. |
| External Input B true | *1C5 |  |
| External Input B false | *1C6 |  |
| External Input A true | *107 |  |
| External Input A false | *1C8 |  |
| Valley value reset | *1C9 |  |
| Store totals \& reset | *1CA |  |

### 9.3 READING AND WRITING TO RAM AND NONVOLATILE MEMORY

## CHARACTERS 1, 2

The Recognition character and Meter Address Code are the same as shown in previous table.

CHARACTER 3: Command character:
G Read bytes from RAM Memory
F Write bytes to RAM Memory (DPM and Scale meter only)
R Read bytes from Upper RAM Memory
Q Write bytes to Upper RAM Memory
X Read words from Non-Volatile Memory
W Write words to Non-Volatile Memory
CHARACTER 4: Number of bytes (G, F, R, Q) or words (X, W)

| Code \# |  |  |  |
| :--- | :--- | :--- | :--- |
| $1=1$ | $9=9$ | $\mathrm{H}=17$ | $\mathrm{P}=25$ |
| $2=2$ | $\mathrm{~A}=10$ | $\mathrm{I}=18$ | $\mathrm{Q}=26$ |
| $3=3$ | $\mathrm{~B}=11$ | $\mathrm{~J}=19$ | $\mathrm{R}=27$ |
| $4=4$ | $\mathrm{C}=12$ | $\mathrm{~K}=20$ | $\mathrm{~S}=28$ |
| $5=5$ | $\mathrm{D}=13$ | $\mathrm{~L}=21$ | $\mathrm{~T}=29$ |
| $6=6$ | $\mathrm{E}=14$ | $\mathrm{M}=22$ | $\mathrm{U}=30$ |
| $7=7$ | $\mathrm{~F}=15$ | $\mathrm{~N}=23$ |  |
| $8=8$ | $\mathrm{G}=16$ | $0=24$ |  |

## CHARACTERS 5, 6

See tables for the RAM MEMORY ADDRESSES and NONVOLATILE MEMORY ADDRESSES with their respective data definitions.

CHARACTERS 7 \& UP: Data to be written ( $F, Q, W$ ).

## GENERAL, READING AND WRITING RAM MEMORY DATA

RAM memory data is read and written as a continuous string of bytes consisting of 2 hex characters ( $0-9, \mathrm{~A}-\mathrm{F}$ ) per byte. Included in the command are the total number of bytes to be transferred and the most significant address in RAM of the continuous string of bytes. The format is:

Read lower RAM data *1Gnaa
Write lower RAM data *1Fnaa<data>
Read upper RAM data *1Rnaa
Write upper RAM data *1Qnaa<data>
where: $\mathrm{n} \quad$ is the number of bytes to be read or written.
aa is the most significant address in RAM of the bytes to be read or written.
<data> is n bytes of 2 hex characters per byte in order from the most to the least significant byte.

The number of bytes $n$ consists of a single code character representing values from 1 to 30 as shown above under CHARACTER 4. The most significant address aa consists of 2 hex characters as shown below under RAM MEMORY ADDRESSES AND DATA DEFINITIONS.

## GENERAL, READING AND WRITING NONVOLATILE MEMORY DATA

Nonvolatile data is read and written as a continuous string of words consisting of 2 bytes or 4 hex characters ( $0-9, A-F)$ per word. Included in the command is the total number of words to be transferred and the most significant address in nonvolatile memory of the continuous string of words. The format is:

Read nonvolatile memory data *1Xnaa (Meter reset occurs after all data is read.)
Write non-volatile memory data *1Wnaa <data> (Meter reset occurs after data is written.) where: $n \quad$ is the number of words to be read or written.
aa is the most significant address in nonvolatile memory of the words to be read or written.
<data> is n words of 2 bytes or 4 hex characters per word in order from the most to the least significant address
The coded number of words $n$ consists of a single character representing values from 1 to 30 as shown under CHARACTER 4. The most significant address aa consists of 2 hex characters as shown under NONVOLATILE MEMORY ADDRESSES.

### 9.4 COMMAND MODE FOR REMOTE DISPLAY OPERATION OF DPM

## OVERVIEW

A DPM can serve as a remote display that responds to values sent via serial communications by a PC or by another DPM in a Master-Slave configuration. In one application, the DPM sends readings to a PC, which then processes the readings and transmits values back to the DPM for display. There are 2 modes in which the DPM may act as a remote display:

## MODE 1: DPM with Signal Conditioner Card and not in Remote Display Mode

$$
\begin{array}{rll}
\text { SETUP (left digit) } & =0 & 4-1 / 2 \text { digit DPM } \\
& =2 & 4-1 / 2 \text { digit DPM with Count by } 10 \\
& =3 & 3-1 / 2 \text { digit DPM }
\end{array}
$$

The baud rate must be set the same as the source. The PC Controller uses the H command to cause the display to halt its normal readings and display the value sent by Serial Communications instead. The DPM must be in the Command mode to receive the data. The data format sent via Serial Communications is:
*\#HSDDDDD.A <CR> where the decimal point is in front, behind (as shown), or between the D's (digits).

A total of 11 characters plus a CR must be included and sent as ASCII characters. Those in quotes below are included as shown. The other symbols represent a range of characters except for CR which is the ASCII character " 0 D ".

* = Command identifier
\# = Device address from 1 to 9 , A to V , or 0 for common address
H = Command letter
S = Sign of value, space (or +) for positive, - for negative value
D = Digit from 0 to 9
* = Decimal point placement and must always be included
$\mathrm{A}=$ Alarm and overload character code, A to H
$<C R>=$ Carriage return character
The following table lists the Alarm and Overload characters.

| ALARM CONDITION | NO OVERLOAD | OVERLOAD |
| :--- | :---: | :---: |
| Neither Alarm on | A | E |
| Alarm 1 only on | B | F |
| Alarm 2 only on | C | G |
| Alarms $1 \& 2$ on | D | H |

If the DPM is in the Continuous mode, it must be put into the Command mode by sending *\#A1 prior to sending the remote display value.

The Remote Display value remains on the display until one of the following occurrences:
a. The command *\#C4 is sent removing the Remote Display value and returning to the normal readings without resetting the DPM.
b. The command *\#CO is sent causing a Cold Reset of the DPM.
c. The command *\#C1 is sent causing a Warm Reset of the DPM.
d. Front panel pushbuttons RESET and MENU are simultaneously pushed to cause a Cold Reset of the DPM.

Notes: After the Remote Display value is entered, the DPM can be put back in the Continuous mode with the command *\#AO without disturbing the display's value. DPM must be in the Command mode for a., b., or c. above. It may be put into the Command mode while displaying a remote display value with the *1A1 command without affecting the display.

If PEAK (manual or external) or ALARM VIEW (manual) is activated while the remote value is being displayed, the peak or alarm value is displayed and cannot be removed except by Remote Display Reset (a., b., or c. above in Command mode) or by manual RESET. If a Remote Display value is sent while in PEAK or ALARM VIEW, it is ignored, but when PEAK or ALARM VIEW is turned off, the Remote Display value comes on.

## MODE 2: DPM with Signal Conditioner Card and in Remote Display Mode

SETUP (left digit) = $1 \quad$ Remote Display mode
The baud rate must be set the same as the source which may be a PC Controller or another DPM. The format is the Slave Format. This is the same as MODE 1 above but without the Command Identifier "*", the address \#, and the Command letter " H ". This is the same format that data is transmitted from a DPM in the Continuous mode. The string of characters must be exactly 8 characters plus the CR in length.

SDDDDD.A <CR>
No commands can be received in this mode but the front panel MENU can be accessed. Any transmissions received other than properly formatted data will result in a meaningless display. Alarm setpoints, Peak readings and external control functions are disabled while the Remote Display value is being displayed. When the DPM is Reset, it displays RESET continuously until data is received.

## DATA FORMAT

## *1HSDDDDD.A

S = Sign, either blank (for + ) or -
$\mathrm{D}=$ Digit from 0 to 9 , five digits total. Always include a decimal point even at the end.
$A=$ Alarm character as defined in 8.4, Mode 1.

### 9.5 COMMAND MODE FOR REMOTE DISPLAY OPERATION OF COUNTER / TIMER

The Counter has 13 Display Modes (0-12). Modes 0-5 are normal measurement modes. Modes 6-12 are dedicated to Remote Display without making any normal readings. In any of the 13 modes, remote display data may be received via RS-232 or RS-485 and be displayed. The remote data requirements and the Remote Display capabilities vary for the different display modes and selected Input Functions. The mode is selected by Menu item "ConFiG" "Digit 3" from the following list:

| Normal Readings While Displaying Remote Data |  | Addressable Commands |
| :--- | :--- | :--- |
| 0 | Normal display, Exponent Overflow | H, K or L |
| 1 | Normal display, 999999 Overflow | H, K or L |
| 2 | 1 right-hand dummy zero | H, K or L |
| 3 | 2 right-hand dummy zeros | H, K or L |
| 4 | Real time clock, multi-format | H, K or L |
| 5 | Real time clock, hh.mm,ss | H, K or L |


| Remote Display Only - No Normal Readings |  | Addressable Commands |
| :--- | :--- | :--- |
| 6 | Addressable remote display | H, K or L commands |
| 7 | Single value remote display | 1 value only |
| 8 | 1st value of value sequence | 1-4 sequential Values |
| 9 | 2nd value of value sequence | 2-4 sequential Values |
| A | 3rd value of value sequence | $3-4$ sequential Values |
| B | 4th value of value sequence | 4 sequential Values |
| C | Programmed to select specific data from | 1 value only |
|  | a data string |  |

The addressable commands of Modes 0-6 can display remote data on one or more Counters having the command address in a multi-point configuration or a single Counter having the command address in a Point-to-point configuration. Modes 7-11 (B) do not use addressable commands, but values only. They are primarily designed for Host Counter or Scale meter to Slave Counter or remote display applications but may be used also in Host Computer to Remote Display Counter configurations. Since the Host Counter may be selected to transmit up to four sequential measurement values, Item 1, Item 2, Item 3 and Peak, (Scale meter transmits up to 3 values) each measurement cycle, Modes 8-11 provide the ability of the Remote Display to extract one of four sequential values and display it.

Modes 0-5 are normal counter modes that may be commanded as follows:

1. H Command. Overrides the normal display reading only.
2. K Command. The value is not displayed, but is stored as Item 3 if Item 3 is not being used. It may then become the source, if selected, for the Alarm comparison and the Analog Output. Item 3 is normally only used for the Batch and Arithmetic functions.

## 3. L Command. Both 1 and 2.

In addition, the $\mathrm{H}, \mathrm{K}, \mathrm{L}$ commands may or may not include a coded Alarm character. If included, this character always overrides the internal Alarm comparisons and determines the alarm indicators, the relay operation and the alarm character sent with the serial communications. Readings continue to be made internally during Remote Display operation and may be received by a Host Computer, manipulated, and returned as remote data. When reset by a *1C4 Command, the display returns to its internal readings, the Alarms to their internal comparisons, the Item 3 value to zero, and the Analog Output as scaled for zero input. A signal conditioner board must be present in these modes to return to normal readings. If no signal conditioner board is present, any Mode setting from 0-5 automatically changes to Mode 6.

Modes 6-11 are used for remote display operation only. No normal readings are made. A signal conditioner board is optional, and if present, is ignored. When reset, the display shows "rESEt" until the first remote display data is received.

Mode 6 is an addressable remote display mode that uses the $\mathrm{H}, \mathrm{K}, \mathrm{L}$ commands.

Mode 7 is not addressable, and data representing a value to be displayed is received in a point-to-point connection. In addition to being displayed, that value is put into Item 3 , where it may be selected for Alarm comparisons and/or for Analog Output. If a Coded Alarm character is included, it overrides the internal alarm comparisons.

Modes 8-11 are able to extract one value of data from a sequence of values, and display that particular value only. Using this mode, multiple slave counters connected to a Host Counter could each be displaying a different Item value. Also, the extracted value is put into Item 3 where it may be selected for Alarm comparisons and/or Analog Output. If a Coded Alarm character is included at the end of the sequence, it is ignored. The remote display reading can only be changed by Meter Reset, a *1C4 Remote display reset command, or another remote display H or L command.

Mode 12 - Remote display "C" allows extraction of data from an ASCII string that contains multiple data values or non-numeric characters. It can accommodate selected Remote Start and Remote Stop characters. Any number of characters between the Remote Start character and the data can be masked OFF. Up to 8 display characters (including sign and DP) can be masked ON. Any number of characters between the last displayed character and the Remote Stop character can be masked OFF.

When CONFIG, CXXX is set, the meter is a Masked Remote Display, and the following parameters determine its operation. These must be set while the meter is set to something other than CONFIG, CXXX, because that is the one setting for which there is no two-way serial communication with the meter. It is suggested to use CONFIG, 6XXX to set the following parameters, and then to use CONFIG, CXXX for operation.

1. Remote Start character (set to 00 if none desired).
2. Remote Stop character (set to 00 if none desired). Note: Only one of the above can be set to 00 .
3. Number of characters following the Remote Start character to be ignored.
4. Number of characters following the ignored characters to be displayed.

Either Instrument Setup.exe or Serial.exe may be used to set the values for the Remote Display C mode. These programs may be downloaded from our website.

## COMMAND FORMATS

The basic two Command formats of the data sent via Serial Communications are:
*\#CSDDDDDD.A<CR><LF> where the decimal point is to the right of any one of the D's (digits).
*\#CSD.DDDEPA<CR><LF> This is the exponential format. The decimal point is fixed. Alarm comparison and Analog Output are not valid in this format.

[^0]S = Sign of value, space (or +) for positive, - for negative value. Sign is optional in display modes $0-7$, required in $8-11$.
D = Digit from 0 to 9 . Number of digits may be $1-6$ in display modes $0-7$, but must be 6 in 8-11.
$P=$ Power of 10. 0-9, A-F where A-F represents 10-15
$\mathrm{A}=$ Optional Alarm Character as defined in section 2.1
<CR> = Carriage return character
<LF> = Optional line feed character (ignored)
These basic Command formats are used when the Remote Display Counter is in display modes $0-6$. The basic Data formats are the same except *\#C is omitted. The basic Data formats are used in display mode 7 .
Single or multiple (2-4) Data formats are used in display modes 8-11. Example:
SDDDDDD.SDDDDDD.SDDDDDD.SDDDDDD.A<CR><LF> <LF> optional, "Ser 3" "Digit 5" = 0 , termination characters only at end of data string or SDDDDDD.<CR><LF>SDDDDDD.<CR><LF>SDDDDDD.<CR><LF>SDDDDDD.A<CR><LF> "Ser 3", Digit $5=1$, termination characters at end of each data item.

### 9.6 RECOGNITION CHARACTER, AND START AND STOP CHARACTERS

The meter recognizes an asterisk ( * ) as the command recognition character. In the counter, another command recognition character may be chosen to make the meter compatible with an existing system. The meter will still respond to an asterisk. For all meters, in continuous mode, a device, such as a printer, may require a start and stop bit to recognize the data string being sent. Normally there is no start bit and the stop bit is a carriage return <CR>. When the Counter is in a normal operating mode (not Remote Display), SER 3, XDXXX can be set for the following combinations:

| D | Command Recognition Character | Continuous Transmission Readings |  |
| :---: | :---: | :---: | :---: |
| 0 | $*$ | None | CR |
| 1 | Selected | None | CR |
| 2 | $*$ | Selected | Selected |
| 3 | Selected | Selected | Selected |

Either Instrument Setup.exe or Serial.exe may be used to set the Command recognition character and the start stop characters. These programs may be downloaded from our website.

## 10. APPENDIX A: DPM MEMORY ADDRESSES AND DATA DEFINITIONS

### 10.1 DPM 1-BYTE RAM MEMORY DATA

$(\mathrm{L})=$ Lower memory, $(\mathrm{U})=$ Upper memory.
The bit assignments below constitute an 8-bit binary number, which needs to be converted to Hex using a program such a Scientific Calculator under MS Windows Accessories. To change an Item in DPM RAM Memory, write the converted Hex value to the Hex Address shown in the left column. To change an Item in Nonvolatile Memory, go to table 10.4, read the existing twobyte word (MS byte and LS byte) from the DPM for the Hex Address which includes the Item to be changed, edit the MS or LS byte as appropriate, and write the edited word back to the Hex Address. Be careful not to overwrite the Sig Cond Type LS byte under Hex Address 15.

| Hex Address | Item Name | Bit Assignment |
| :---: | :---: | :---: |
| DE (L) | Configuration |  |
| BF (L) | Analog Setup | Bit 7 6 5 4 3 2 1 0   <br>        0 Analog output unfiltered  <br>        1 Analog output filtered  <br>      0 0   $0-20 \mathrm{~mA}$ current output <br>      0 1   $0-10 \mathrm{~V}$ voltage output <br>      1 0  4-20 mA current output  <br>      1 1  -10V to +10 V output  |


| 69 (L) | Serial Cnfg3 |  |
| :---: | :---: | :---: |
| 35 (L) | Decimal Point | 01 Byte values in hex <br> 02 XXXXX. <br> 03 hex characters/byte) <br> XXXX.X  <br> 04  <br> 05 XXX.XX <br> 06  <br> 06 X.XXXX <br>   |
| 34 (L) | Lockout2 <br> 0 = unlocked <br> 1 = locked |  |
| 33 (L) | Lockout1 <br> 0 = unlocked <br> 1 = locked | Bit 6 5 4 3 2 1 0 <br>        1 Menu item \& front panel lockout <br> Offset, Lo \& Hi readings <br> Scale, Lo In, Hi In         <br>       1   Filter Setup <br>      1    Setup, Config \& Decimal Point <br> InPut Menu Item |



| 2 F (L) | Filter |  |
| :---: | :---: | :---: |
| 2D (L) | Setup |  |


| 09 (U) | Setup1* <br> * Cannot be written to RAM | Bit7 6 5 4 3 2 1 0         <br>       0 0 $4-1 / 2$ digit display ( $0.1^{\circ}$ temp.) <br>       0 1 Remote display <br>       1 0 $4-1 / 2$ digit count by $10\left(0.01^{\circ} \mathrm{t}.\right)$ <br>      1 1 $3-1 / 2$ digit display $\left(1^{\circ}\right.$ temp.)  |
| :---: | :---: | :---: |
| OD (U) | Alarm Confg4 |  |
| OC (U) | Alarm Confg3 |  |


| OB (U) | Alarm Confg2 |  |
| :---: | :---: | :---: |
| OA (U) | Alarm Confg 1 |  |


| 00 (U) | Serial Cnfg4 | Bit 76 | $\begin{array}{ll} 5 & 4 \\ \hline \end{array}$ | $\begin{array}{llll} 3 & 2 & 1 & 0 \\ & & 0 & 0 \\ & & 0 & 1 \\ & & 1 & 0 \\ 0 & 0 & & \\ 0 & 1 & & \\ 1 & 0 & & \end{array}$ | Serial Protocol <br> No Parity <br> Odd Parity <br> Even Parity <br> Custom ASCII protocol (8 bits) <br> Modbus RTU protocol (8 bits) <br> Modbus ASCII protocol (7 bits) <br> 1 s Modbus ASCII gap timeout <br> 3 s Modbus ASCII gap timeout <br> 5 s Modbus ASCII gap timeout <br> 10 s Modbus ASCII gap timeout |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 35 (U) | Modbus Addr. | 00 to FF |  |  | Modbus address 0-255 (in Hex format) |

### 10.2 DPM 3-BYTE RAM MEMORY DATA

Format for all items except Scale Factor: MS byte
XX
Mid byte
LS byte
Format for Scale Factor:
*X
XX
XX

The 4-bit MS nibble "*" sets the polarity and decimal point according to the following table:

| Positive | Negative | Decimal Point |
| :---: | :---: | :---: |
| 1 | 9 | XXXXX. |
| 2 | A | XXXX.X |
| 3 | B | XXX.XX |
| 4 | C | XX.XXX |
| 5 | D | X.XXXX |
| 6 | E | .XXXXX |

Note: Hex values are 2's complement and absolute values.

### 10.3 DPM HEX ADDRESSES

| MS | Mid | LS | Description |
| :---: | :---: | :---: | :--- |
| A1 (L) | A0 | $9 F$ | Analog high value |
| 9E (L) | $9 D$ | 9 D | Analog low value |
| 1B (U) | 1A | 19 | Deviation, Alarm4 |
| 18 (U) | 17 | 16 | Deviation, Alarm3 |
| 9B (L) | 9 A | 99 | Deviation, Alarm2 |
| 98 (L) | 97 | 96 | Deviation, Alarm1 |
| 8F (L) | 8 E | 8 D | Offset value |
| 8C (L) | 8 B | 8 A | Scale factor |
| 15 (U) | 14 | 13 | Setpoint4 |
| 12 (U) | 11 | 10 | Setpoint3 |
| 89 (L) | 88 | 87 | Setpoint2 |
| 86 (L) | 85 | 84 | Setpoint1 |

10.4 DPM NONVOLATILE MEMORY ADDRESSES (2 bytes/address)

| Hex Addr | MS Byte | LS Byte | Stored As |
| :---: | :---: | :---: | :---: |
| 75 | Setup1 | Serial Confg3 | Bits |
| 74 | Deviation4 Byte 3 | Deviation4 Byte 2 | Magnitude |
| 73 | Deviation4 Byte 1 | Deviation3 Byte 3 | Magnitude |
| 72 | Deviation3 Byte 2 | Deviation3 Byte 1 | Magnitude |
| 71 | Setpoint4 Byte 3 | Setpoint4 Byte 2 | 2's Complement |
| 70 | Setpoint4 Byte 1 | Setpoint Byte 3 | 2's Complement |
| 6 F | Setpoint3 Byte 2 | Setpoint3 Byte 1 | 2's Complement |
| 6 E | Alarm Cnfg4 | Alarm Confg 3 | Bits |
| 6D | Version (read only) | M Type (read only) | Byte |
| 36 | Tare Setup | Analog Type | Bits |
| 35 | Serial Cnfg4 (Bits) | Modbus Address (Byte) |  |
| 18 | Deviation2 Byte 3 | Deviation2 Byte 2 | Magnitude |
| 17 | Deviation2 Byte 1 | Deviation1 Byte 3 | Magnitude |
| 16 | Deviation1 Byte 2 | Deviation1 Byte 1 | Magnitude |
| 15 | Configuration | Sig Cond Type (do not change) | Bits |
| 14 | Analog Setup | System Decimal Point | Bits |
| 13 | Lockout2 | Lockout1 | Bits |
| 12 | Serial Cnfg2 | Serial Cnfg1 | Bits |
| 11 | Options | Filter | Bits |
| 10 | Setup | Input Type | Bits |
| OF | Alarm Cnfg Byte 2 | Alarm Cnfg1 | Bits |
| OE | Analog High Byte 3 | Analog High Byte 2 | 2's Complement |
| OD | Analog High Byte 1 | Analog Low Byte 3 | 2's Complement |
| OC | Analog Low Byte 2 | Analog Low Byte 1 | 2's Complement |
| OB | High Read Byte 3 | High Read Byte 2 | 2's Complement |
| OA | High Read Byte 1 | High In Byte 3 | 2's Complement |
| 09 | High In Byte 2 | High In Byte 1 | 2's Complement |
| 08 | Low Read Byte 3 | Low Read Byte 2 | 2's Complement |
| 07 | Low Read Byte 1 | Low In Byte 3 | 2's Complement |
| 06 | Low In Byte 2 | Low In Byte 1 | 2's Complement |
| 05 | Offset Byte 3 | Offset Byte 2 | 2's Complement |
| 04 | Offset1 (2's Comp) | Scale Factor3 (Sign+DP+Mag) |  |
| 03 | Scale Factor2 | Scale Factor1 | Sign+DP+Mag |
| 02 | Setpoint2 Byte 3 | Setpoint2 Byte 2 | 2's Complement |
| 01 | Setpoint2 Byte 1 | Setpoint1 Byte 3 | 2's Complement |
| 00 | Setpoint1 Byte 2 | Setpoint1 Byte 1 | 2's Complement |

## 11. APPENDIX B: COUNTER / TIMER MEMORY ADDRESSES AND DATA DEFINITIONS

### 11.1 COUNTER / TIMER 1-BYTE RAM MEMORY DATA

$(\mathrm{L})=$ Lower memory, $(\mathrm{U})=$ Upper memory
The bit assignments below constitute an 8-bit binary number, which needs to be converted to Hex using a program such a Scientific Calculator under MS Windows Accessories. To change an Item in Counter / Timer RAM Memory, write the converted Hex value to the Hex Address shown in the left column. To change an Item in Nonvolatile Memory, go to table 11.4, read the existing two-byte word (MS byte and LS byte) from the Counter / Timer for the Hex Address which includes the Item to be changed, edit the MS or LS byte as appropriate, and write the edited word back to the Hex Address.

| Hex Address | Item Name | Bit Assignment |
| :---: | :---: | :---: |
| 43 (L) | Resolution | $\begin{array}{\|lllllllll} \hline \text { Bit } 7 & 6 & 5 & 4 & 3 & 2 & 1 & 0 & \text { Multiplier } \\ & & & & & & & 0 & 0.00001 \\ & & & & & & & 1 & 0.0001 \\ & & & & & & 1 & 0 & 0.001 \\ & & & & & & 1 & 1 & 0.01 \\ & & & & & 1 & 0 & 0 & 0.1 \\ & & & & & 1 & 0 & 1 & 1 \\ & & & & & 1 & 1 & 0 & 10 \\ & & & & & 1 & 1 & 1 & 100 \\ & & & & 1 & 0 & 0 & 0 & 1000 \\ & & & & 1 & 0 & 0 & 1 & 10000 \\ & & & 1 & 0 & 1 & 0 & & 100000 \end{array}$ |
| 42 (L) | Recog. Char. | ASCII value of custom recognition character |
| 41 (L) | Slope | Bit 7 6 5 4 3 2 1 0   <br>        0 Positive slope Channel B  <br>           <br>  Negative slope Channel B         <br>       0  Positive slope Channel A  <br>          Negative slope Channel A |
| 3E (L) | Scale Multiplier | Bits 3-0 $=0-\mathrm{A}$ SCALE1 multiplier <br> Bits 7-4 $=0-\mathrm{A}$ SCALE2 multiplier <br> $0-\mathrm{A}:$ Same multiplier as for Resolution |


| 3D (L) | Analog Setup | Bit 7 6 5 4 3 2 1 0 Analog Output Source  <br>       0 0 Filtered Item  <br>       0 1 Item 1  <br>      1 0 Item 2   <br>       1 1 Item 3  <br>      0    0 to 20 mA output <br>     1   0 to 10 V output   <br>     1 0   4 to 20 mA output  <br>     1 1   -10V to 10 V output  |
| :---: | :---: | :---: |
| 3 C ( L | Source | Bit 7 6 5 4 3 2 1 0  <br>         Compare Setpoint 2 to: <br>       0 0 Filtered Item <br>      0 1 Item 1  <br>      1 0 Item 2  <br>      1 1 Item 3  <br>         Compare Setpoint 1 to: <br>    0 0   Filtered Item  <br>    0 1   Item 1  <br>    1 0   Item 2  <br>    1 1   Item 3  |
| 36 (L) | Lockout2 <br> 0 = unlocked <br> 1 = locked |  |
| 35 (L) | Lockout1 <br> 0 = unlocked <br> 1 = locked |  |


| 34 (L) | Configuration | $\left.\left.\begin{array}{ccccccccl}\text { Bit } 7 & 6 & 5 & 4 & 3 & 2 & 1 & 0 & \\ & & & & & & & 0 & \\ \text { Enable cutoff of VF totalizing }\end{array}\right] \begin{array}{l}\text { Totalize all VF values }\end{array}\right]$ |
| :---: | :---: | :---: |
| 33 (L) | Serial Cnfg3 |  |


| 00 U | Serial Cnfg 4 |  |
| :---: | :---: | :---: |
| 32 (L) | Serial Cnfg2 |  |
| 31 (L) | Serial Cnfg1 |  |
| 30 (L) | Options | Do not use. This byte is determined by installed option boards. |
| 2 F (L) | Filter | $\begin{array}{lllllllllll}\text { Bit } 7 & 6 & 5 & 4 & 3 & 2 & 1 & 0 & \text { Approximate time constant: } \\ & & & & & 0 & 0 & 0 & \text { No filtering } \\ & & & & 0 & 0 & 1 & 0.1 \mathrm{sec}\end{array}$ |


|  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 2E (L) | Setup | Bit 76 $\begin{array}{rr}  & 0 \\ & 1 \\ 0 & \\ 1 & \end{array}$ | $5$ | 4 | $\begin{array}{llll} 3 & 2 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 \\ 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 1 & 1 & 0 & 1 \\ 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 \end{array}$ <br> Scale2, Offse <br> Scale2, Offse <br> Scale1, Offs <br> Scale1, Offse <br> Blank leading <br> Display leading <br> Zero the tota <br> Restore tota | EXT IN 1 <br> Meter Reset <br> Meter Reset <br> Meter Reset <br> Function Rese <br> Function Rese <br> Function Rese <br> Hold <br> Hold <br> Peak Display <br> Meter Reset <br> Function Rese <br> Hold <br> Peak Display <br> Display Blank <br> Display item\#2 <br> t2 entered directly <br> t2 using Coordin <br> t1 entered directly <br> t1 using Coord <br> zeros <br> ng zeros <br> at power on <br> at power-on | EXT IN 2 <br> Function Reset Peak Display External Gate Hold Peak Display External Gate Peak Display External Gate External Gate Display Blank Display Blank Display Blank Display Blank External Gate Display item\#3 ates of 2 points ates of 2 points |



| OD U | Alarm Cnfg 4 | Same as for DPM, page 35 |
| :---: | :---: | :---: |
| OC U | Alarm Cnfg 3 | Same as for DPM, page 35 |
| OA U | Alarm Cnfg 1 |  |

### 11.2 COUNTER / TIMER 2-BYTE RAM DATA TABLE

| Hex MS | Hex LS | Name | Hex Range | Dec Range |
| :---: | :---: | :---: | :---: | :--- |
| 40 | $3 F$ | Pulses | $0000-$ EA5F | $0-59999$ Positive magnitude (Units $=1$ ) |
| $3 A$ | 39 | Timeout | $0000-4 \mathrm{EF1F}$ | $0-19999$ Positive magnitude (Units $=0.01 \mathrm{sec}$ ) |
| 38 | 37 | Gatetime | $0000-4 \mathrm{E} 1 \mathrm{~F}$ | $0-19999$ Positive magnitude (Units $=0.01 \mathrm{sec}$ ) |

### 11.3 COUNTER / TIMER 3-BYTE RAM DATA TABLE

| Hex MS | Hex Mid | Hex LS | Name | Stored as |
| :---: | :---: | :---: | :--- | :--- |
| B0 (L) | AF | AE | Deviation2 (values always+) (Hysteresis2) |  |
| AA (L) | A9 | A8 | Offset2 |  |
| 9E (L) | 9D | 9C | Setpoint2 | Values stored |
| AD (L) | AC | AB | Deviation1 (values always+) (Hysteresis1) | as 3-byte 2's |
| A4 (L) | A3 | A2 | Offset1 | complement |
| 9B (L) | 9A | 99 | Setpoint1 |  |
| 1B U | 1A | 19 | Deviation4 |  |
| 18 U | 17 | 16 | Deviation3 |  |


| $15(\mathrm{U})$ | 14 | 13 | Setpoint 4 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| $12(\mathrm{U})$ | 11 | 10 | Setpoint 3 |  |
| A7 (L) | A6 | A5 | Scale2 | Values stored as sign (MS bit) + |
| A1 (L) | A0 | $9 F$ | Scale1 | magnitude (all other bits), fixed DP $=6$ |

11.4 COUNTER / TIMER NON-VOLATILE MEMORY ADDRESSES (2 bytes / address)

|  | Byte 3 |  |  | Byte 2 | Byte 1 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Magnitude (Mag) |  | XXX X | XXXX | XXXX XXXX | XXXX XXXX | $\begin{aligned} & S=\text { Sign } \\ & \text { Sign }=1 \text { for negative } \\ & D P=1 \text { for DDDDDD. } \\ & D P=6 \text { for D.DDDDD } \end{aligned}$ |
| Sign + Magnitude (S+M) | X | XXX | XXXX | XXXX XXXX | XXXX XXXX |  |
|  | S | Magnitude |  |  |  |  |
| $\begin{gathered} \text { Sign + DP + Magnitude } \\ (S+D P+M) \end{gathered}$ | X | XXX | XXXX | XXXX XXXX | XXXX XXXX |  |
|  | S | DP | Magnitude |  |  |  |
| 2's Complement (2's C) |  | XXX X | XXXX | XXXX XXXX | XXXX XXXX |  |


| Hex Addr | MS Byte of NV RAM | Stored As | LS Byte of NV RAM | Stored As |
| :---: | :--- | :---: | :--- | :---: |
| 74 | Deviation4 Byte 3 | Mag | Deviation4 Byte 2 | Mag |
| 73 | Deviation4 Byte 1 | Mag | Deviation3 Byte 3 | Mag |
| 72 | Deviation3 Byte 2 | Mag | Deviation3 Byte 1 | Mag |
| 71 | Setpoint4 Byte 3 | 2's C | Setpoint4 Byte 2 | 2's C |
| 70 | Setpoint4 Byte 1 | 2's C | Setpoint3 Byte 3 | 2's C |
| 6F | Setpoint3 Byte 2 | 2's C | Setpoint3 Byte 1 | 2's C |
| 6E | Alarm Confg4 | Bits | Alarm Confg3 | Bits |
| 6D | Version (read only) | Byte | M Type (read only) | Byte |
| 6C | T Stop | Byte | T Start | Byte |
| 6B | R Show | Byte | R Skip | Byte |
| 6A | R Stop | Byte | R Start | Byte |
| 35 | Analog High2 Byte 3 | 2's C | Analog High2 Byte 2 | 2's C |
| 34 | Analog High2 Byte 1 | 2's C | Analog Low2 Byte 3 | 2's C |
| 33 | Analog Low3 Byte 2 | 2's C | Analog Low2 Byte 1 | 2's C |
| 32 | Serial Confg4 | Bits | Modbus Address | Byte |
| 31 | Total A Byte 6 | Mag | Total A Byte 5 | Mag |
| 30 | Total A Byte 4 | Mag | Total A Byte 3 | Mag |
| 2F | Total A Byte 2 | Mag | Total A Byte 1 | Mag |
| 2E | Total B Byte 6 | Mag | Total B Byte 5 | Mag |
| 2D | Total B Byte 4 | Mag | Total B Byte 3 | Mag |
| 2C | Total B Byte 2 | Mag | Total B Byte 1 | Mag |
| 2A | Do not use | --- | Analog Type | Bits |


| 29 | Cutoff Byte 2 | Mag | Cutoff Byte 1 | Mag |
| :---: | :---: | :---: | :---: | :---: |
| 28 | Recog Character | Byte | System Decimal Point | Bits |
| 27 | Do not use | Bits | Resolution | Bits |
| 26 | Display Item | Bits | Slope | Bits |
| 25 | Pulses Byte 2 | Mag | Pulses Byte 1 | Mag |
| 24 | Scale Multiplier | Bits | Analog Output Setup | Bits |
| 23 | Source | Bits | Batch | Bits |
| 22 | Timeout Byte 2 | Mag | Timeout Byte 1 | Mag |
| 21 | Gate Time Byte 2 | Mag | Gate Time Byte 1 | Mag |
| 20 | Lockout2 | Bits | Lockout1 | Bits |
| 1F | Config | Bits | Serial Config3 | Bits |
| 1E | Serial Config2 | Bits | Serial Config1 | Bits |
| 1D | Options | Bits | Filter | Bits |
| 1 C | Setup | Bits | Input Type | Bits |
| 1B | Alarm Config 2 | Bits | Alarm Config1 | Bits |
| 1A | Analog High Byte 3 | 2 's C | Analog High Byte 2 | 2 's C |
| 19 | Analog High Byte 1 | 2 's C | Analog Low Byte 3 | 2 's C |
| 18 | Analog Low Byte 2 | 2 's C | Analog Low Byte 1 | 2 's C |
| 17 | Deviation 2 Byte 3 | Mag | Deviation2 Byte 2 | Mag |
| 16 | Deviation 2 Byte 1 | Mag | Deviation1 Byte 3 | Mag |
| 15 | Deviation 1 Byte 2 | Mag | Deviation1 Byte 1 | Mag |
| 14 | Offset2 Byte 3 | 2 's C | Offset2 Byte 2 | 2 's C |
| 13 | Offset2 Byte 1 | 2 's C | Scale2 Byte 3 | S+M |
| 12 | Scale2 Byte 2 | S+M | Scale2 Byte 1 | S+M |
| 11 | Offset1 Byte 3 | 2's C | Offset1 Byte 2 | 2's C |
| 10 | Offset1 Byte 1 | 2 's C | Scale1 Byte 3 | S+M |
| OF | Scale1 Byte 2 | S+M | Scale1 Byte 1 | S+M |
| OE | Setpoint2 Byte 3 | 2 's C | Setpoint2 Byte 2 | 2 's C |
| OD | Setpoint2 Byte 1 | 2 's C | Setpoint1 Byte 3 | 2 's C |
| OC | Setpoint1 Byte 2 | 2 's C | Setpoint1 Byte 1 | 2 's C |
| OB | High Read2 Byte 3 | 2 's C | High Read2 Byte 2 | 2's C |
| OA | High Read2 Byte 1 | 2 's C | High In2 Byte 3 | S+DP+M |
| 09 | High In2 Byte 2 | S+DP+M | High In2 Byte 1 | S+DP+M |
| 08 | Low Read2 Byte 3 | 2's C | Low Read2 Byte 2 | 2's C |
| 07 | Low Read2 Byte 1 | 2's C | Low In2 Byte 3 | S+DP+M |
| 06 | Low In2 Byte 2 | S+DP+M | Low In2 Byte 1 | S+DP+M |
| 05 | High Read1 Byte 3 | 2's C | High Read1 Byte 2 | 2's C |
| 04 | High Read1 Byte 1 | 2's C | High In1 Byte 3 | S+DP+M |
| 03 | High In1 Byte 2 | S+DP+M | High In1 Byte 1 | S+DP+M |
| 02 | Low Read1 Byte 3 | 2 's C | Low Read1 Byte 2 | 2's C |
| 01 | Low Read1 Byte 1 | 2's C | Low In1 Byte 3 | S+DP+M |
| 00 | Low In1 Byte 2 | S+DP+M | Low In1 Byte 1 | S+DP+M |

## 12. APPENDIX C: WEIGHT METER MEMORY ADDRESSES

 AND DATA DEFINITIONS
### 12.1 WEIGHT METER 1-BYTE RAM MEMORY DATA

$(\mathrm{L})=$ Lower memory, $(\mathrm{U})=$ Upper memory
The bit assignments below constitute an 8-digit binary number, which needs to be converted to Hex using a program such a Scientific Calculator under MS Windows Accessories. To change an Item in Counter / Timer RAM Memory, write the converted Hex value to the Hex Address shown in the left column. To change an Item in Nonvolatile Memory, go to table 11.3, read the existing two-byte word (MS byte and LS byte) from the Counter/Timer for the Hex Address which includes the Item to be changed, edit the MS or LS byte as appropriate, and write the edited word back to the Hex Address.

$\left.\begin{array}{|l|l|lllllllllll|}\hline \text { 6B (L) } & \text { Config } & \text { Bit } 7 & 6 & 5 & 4 & 3 & 2 & 1 & 0 & & \\ & & & & & & & & & & 0 & \text { Enable Adaptive Filtering } \\ & & & & & & & & & 1 & & \text { Disable Adaptive Filtering } \\ \text { Peak of Net Value }\end{array}\right]$

|  |  |  |
| :---: | :---: | :---: |
| 35 (L) | Decimal Point | $\begin{array}{\|llllllllll\|} \hline \text { Bit } 7 & 6 & 5 & 4 & 3 & 2 & 1 & 0 & \text { Meter Display } \\ & & & & & 0 & 0 & 1 & \text { XXXXX. (dec point not displayed) } \\ & & & & & 0 & 1 & 0 & \text { XXXX.X } \\ & & & & & 0 & 1 & 1 & \text { XXX.XX } \\ & & & & & 1 & 0 & 0 & \text { XX.XXX } \\ & & & & & 1 & 0 & 1 & \text { X.XXXX } \\ & & & & 1 & 1 & 0 & \text {.XXXXX } \end{array}$ |
| OA (U) | Alarm Confg1 |  |


|  |  | 11 Relay1 Off when Al1 active, Relay2 Off when Al2 active |
| :---: | :---: | :---: |
| OB (U) | Alarm Confg2 |  |
| OD (U) | Alarm Cnfg 4 | Same as for DPM, page 35 |
| OC (U) | Alarm Cnfg 3 | Same as for DPM, page 35 |
| BF (L) | Analog Output Setup |  |
| 31 (L) | Serial Cnfg1 |  |


|  |  | 0 0 0 300 baud <br> 0 0 1 600 baud <br> 0 1 0 1200 baud <br> 0 1 1 2400 baud <br> 1 0 0 4800 baud <br> 1 0 1 9600 baud <br> 1 1 0 19200 baud <br> 0   Send Unfiltered Value <br> 1   Send Filtered Value |
| :---: | :---: | :---: |
| 32 (L) | Serial Cnfg2 |  |
| 6A (L) | Serial Cnfg3 |  |
| 00 (U) | Serial Cnfg4 |  |


|  |  | 0 1 3 s Modbus ASCII Gap Timeout <br> 1 0 5 s Modbus ASCII Gap Timeout <br> 1 1 10 s Modbus ASCII Gap Timeout |
| :---: | :---: | :---: |
| 33 (L) | Lockout1 0 = Enabled 1 = Disabled |  |
| 34 (L) | Lockout2 <br> 0 = Enabled <br> 1 = Disabled |  |

12.3 WEIGHT METER 3-BYTE RAM MEMORY DATA (3 Bytes / Item)

All numeric values except scale factor utilize a 2's complement, 3-byte Hex format, where the MS byte, Mid byte and LS byte each consist of two Hex nibbles: XX XX XX.

Polarity and decimal point for scale are set by the most significant Hex nibble of the most significant byte (leftmost byte) as follows:

| MS Bit | Polarity \& Dec Pt |
| :---: | :---: |
| 1 | XXXXX. |
| 2 | XXXX.X |
| 3 | XXX.XX |
| 4 | XX.XXX |
| 5 | X.XXXX |
| 6 | . XXXXX |
| 9 | - XXXXX. |
| A | - XXXX.X |
| B | - XXX.XX |
| C | - XX.XXX |
| D | - X.XXXX |
| E | .- XXXXX |

Hex addresses for numeric values are also in the 3-byte Hex format, as explained in 12.1, as follows:

| Numeric Value | MS Byte | Mid Byte | LS Byte |
| :--- | :---: | :---: | :---: |
| Analog high value | A1 (L) | A0 | 9 F |
| Analog low value | 9E (L) | 9 D | 9 C |
| Setpoint 2 Diff | 9B (L) | 9 A | 99 |
| Setpoint 1 Diff | 98 (L) | 97 | 96 |
| Offset value | 8F (L) | 8 E | 8 D |
| Scale factor | 8C (L) | 8 B | 8 A |
| Setpoint4 | 15 (U) | 14 | 13 |
| Setpoint3 | 12 (U) | 11 | 10 |
| Setpoint2 | 89 (L) | 88 | 87 |
| Setpoint1 | 86 (L) | 85 | 84 |
| Tare value | E3 (L) | E2 | E1 |

12.4 WEIGHT METER NONVOLATILE MEMORY HEX ADDRESSES (2 Bytes / Address)

Please see the 1 Byte RAM Data Table for bit definitions.

| Hex Address | MS Byte |  |
| :--- | :--- | :--- |
| $1 D$ | Tare3 | LS Byte |
| 1 C | Tare1 | Sare2 |
| $1 B$ | Spare |  |
| 18 | Serial Cnfg 3 | Count |
| 17 | Setpoint2 Diff 3 | Setpoint2 Diff 2 |
| 16 | Setpoint2 Diff 1 | Setpoint1 Diff 3 |
| 15 | Configuration | Setpoint1 Diff 1 |
| 14 | Analog Setup | Signal Conditioner Type (do not change) |
| 13 | Sockout 2 | Lockout Decimal Point |
| 12 | Serial Cnfg 2 | Serial Cnfg 1 |
| 11 | Options | Filter |
| 10 | Setup | Input Type |
| 0 F | Alarm Cnfg 2 | Alarm Cnfg 1 |
| 0 E | Analog High 3 | Analog High 2 |
| $0 D$ | Analog High 1 | Analog Low 3 |
| 0 C | Analog Low 2 | Analog Low 1 |
| $0 B$ | High Reading 3 | High Reading 2 |
| 0 A | High Reading 1 | High Input 3 |
| 09 | High Input 2 | High Input 1 |
| 08 | Low Reading 3 | Low Reading 2 |
| 07 | Low Reading 1 | Low Input 3 |
| 06 | Low Input 2 | Low Input 1 |
| 05 | Offset 3 | Offset 2 |
| 04 | Offset 1 | Scale Factor 3 |
| 03 | Scale Factor 2 | Scale Factor 1 |
| 02 | Setpoint2 3 | Setpoint2 2 |
| 01 | Setpoint2 1 | Setpoint1 3 |
| 00 | Setpoint 1 2 | Setpoint1 1 |
| 35 | Serial Cnfg 4 | Modbus Address |
| 36 | Spare | Analog Output Type |

## 13. RECOMMENDED CONVERTER SUPPLIER

## B \& B Electronics Manufacturing Co.

707 Dayton Road, Ottawa, IL 61350. Phone: (815) 433-5100, Fax: (815) 433-5109, Website: www.bb-elec.com. B \& B offers a variety of RS485-to-RS232 converters, RS232-to-RS485 converters, RS485-to-USB converters, and RJ11 to 9-pin adapters. B \& B Model 4850T9L is the recommended RS485-to-RS232 converter for use with products covered in this manual.

## WARRANTY

Yokogawa Corporation of America warrants its products against defects in materials or workmanship for a period of one year from the date of purchase.

In the event of a defect during the warranty period, the unit should be returned, freight prepaid (and all duties and taxes) by the Buyer, to the authorized Yokogawa distributor where the unit was purchased. The distributor, at its option, will repair or replace the defective unit. The unit will be returned to the buyer with freight charges prepaid by the distributor.

## LIMITATION OF WARRANTY

The foregoing warranty shall not apply to defects resulting from:

1. Improper or inadequate maintenance by Buyer.
2. Unauthorized modification or misuse.
3. Operation outside the environmental specifications of the product.
4. Mishandling or abuse.

The warranty set forth above is exclusive and no other warranty, whether written or oral, is expressed or implied. Yokogawa specifically disclaims the implied warranties of merchantability and fitness for a particular purpose.

## EXCLUSIVE REMEDIES

The remedies provided herein are Buyer's sole and exclusive remedies. In no event shall Yokogawa be liable for direct, indirect, incidental or consequential damages (including loss of profits) whether based on contract, tort, or any other legal theory.


[^0]:    * $=$ Recognition character
    \# $=$ Device address from 1-9, A to V , or 0 for common address.
    $\mathrm{C}=$ Command letter H, K, L.

